

Arterial impulse model for the BOLD response to brief neural activation

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ABSTRACT

The blood oxygen level dependent (BOLD) signal evoked by brief neural stimulation, the hemodynamic response function (HRF), is a critical feature of neurovascular coupling. The HRF is directly related to local transient changes in oxygen supplied by cerebral blood flow (CBF) and oxygen demand, the cerebral metabolic rate of oxygen (CMRO₂). Previous efforts to explain the HRF have relied upon the hypothesis that CBF produces a non-linear venous dilation within the cortical parenchyma. Instead, the observed dynamics correspond to prompt arterial dilation without venous volume change. This work develops an alternative biomechanical model for the BOLD response based on the hypothesis that prompt upstream dilation creates an arterial flow impulse amenable to linear description. This flow model is coupled to a continuum description of oxygen transport. Measurements using high-resolution fMRI demonstrate the efficacy of the model. The model predicts substantial spatial variations of the oxygen saturation along the length of capillaries and veins, and fits the varied gamut of measured HRFs by the combined effects of corresponding CBF and CMRO₂ responses. Three interesting relationships among the hemodynamic parameters are predicted. First, there is an offset linear correlation with approximately unity slope between CBF and CMRO₂ responses. Second, the HRF undershoot is strongly correlated to the corresponding CBF undershoot. Third, late-time-CMRO₂ response can contribute to a slow recovery to baseline, lengthening the HRF undershoot. The model provides a powerful mathematical framework to understand the dynamics of neurovascular and neurometabolic responses that form the BOLD HRF.

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Introduction

Neural activity leads to an increase in local cerebral blood flow (CBF) to compensate for the energy demands of the corresponding brain region. This local functional hyperemia, called neurovascular coupling, provides a means to infer brain activity. Various imaging modalities, such as functional magnetic resonance imaging (fMRI), optical imaging, and positron emission tomography (PET), use neurovascular coupling responses to identify and quantify local neural activation.

fMRI is widely used for human brain research because it is safe and non-invasive, yet provides good spatiotemporal resolution. Most fMRI relies on the blood-oxygen-level dependent (BOLD) signal: local microvascular hyperemia leads to less paramagnetic deoxyhemoglobin, thus reducing magnetic field distortion and increasing the MR signal observed during a gradient-recalled echo sequence (Buxton, 2013). The BOLD signal is, therefore, directly related to local transient changes in the oxygen supplied by CBF. In addition, the BOLD signal is affected by oxygen demand, the cerebral metabolic rate of oxygen (CMRO₂), because oxygen diffuses from the blood as it passes through the activated brain region. However, the quantitative relationship between the BOLD response, CBF, and CMRO₂ remains unclear. In fact, it has long been known that the observed increase in CBF evoked by neural activity is

substantially larger than the corresponding increase in CMRO₂; this has been termed “neurovascular uncoupling” (Fox and Raichle, 1986). This apparent physiological mismatch has complicated attempts to understand the underlying mechanism of the BOLD response.

The response evoked by brief neural activity is called the hemodynamic response function (HRF). Analysis of event-related fMRI, which relies on sequences of episodic neural activations, is particularly dependent on a complete understanding of the HRF. The HRF typically includes three stereotypical temporal phases: initial dip or delay (Frostig et al., 1990; Hu and Yacoub, 2012; Menon et al., 1995), then a hyperoxic peak, followed by an undershoot (Buxton, 2012; Kruger et al., 1996; van Zijl et al., 2012) with possible oscillatory ringing (Ress et al., 2009; Thompson et al., 2003). The time scale of the HRF is ~20–30 s when evoked by <5-s stimulation.

Most attempts to explain and model the BOLD response also assume that neural activity results in changes in cerebral blood volume (CBV), as well as changes in CBF and CMRO₂. The volume changes have generally been associated with venous vasodilation, motivated by a host of steady-state, slow time-scale measurements showing a nonlinear relationship between CBV and CBF (Buxton et al., 1998; Grubb et al., 1974; Kety and Schmidt, 1948; Zheng et al., 2005; Zheng et al., 2002). Based on this assumption, the calibrated-BOLD approach was introduced to estimate CMRO₂ and CBV from measurements of BOLD signal and CBF (Davis et al., 1998). The model used two non-linear relationships to describe the BOLD signal, one giving venous blood-oxygen

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changes, and the other giving venous CBV changes driven by a CBF response. This mathematical framework has been a basis of most biophysical models to describe the BOLD signal with the underlying dynamics of CBF, CMRO₂ and CBV changes. The “balloon model” has been the most popular, postulating that brain activation causes increased CBF leading to non-linear venous dilation (Buxton et al., 1998). It considered both intra- and extra-vascular compartments as sources of the BOLD signal. Mandeville et al. (1999) measured CBF using laser-Doppler flowmetry and inferred CBV using fMRI, and introduced a similar model based upon delayed compliance to fit the experimental data. Recently, many non-linear models have been introduced with greater elaboration and sophistication (Buxton et al., 2004; Griffeth and Buxton, 2011; Kong et al., 2004; Obata et al., 2004; Zheng et al., 2002; Zheng and Mayhew, 2009). Some balloon models also include convection–diffusion oxygen transport (Huppert et al., 2007). Very recently, a convection–diffusion transport model (Fang et al., 2008) was applied to two-photon measurements of the vascular network to permit detailed evaluation of BOLD responses from extravascular compartments (Gagnon et al., 2015).

However, the underlying assumption of the non-linear CBV to CBF relationship for the comparatively fast time scale of the HRF remained untested until recently. Various forms of *in vivo* optical imaging of individual blood vessels have demonstrated that there are no significant venous volume changes caused by brief brain activation (Drew et al., 2011; Fernandez-Klett et al., 2010; Hillman et al., 2007; Vazquez et al., 2010). These experimental findings consistently indicate that venous volume changes are not a source of the BOLD signal for brief neural activation, and support the hypothesis that upstream pial artery dilation generates a transient CBF response to compensate the local oxygen demand in parenchyma. Such arterial vasodilation can create an underdamped flow response because it involves larger vessel diameters (e.g., >200 μm) and flow speeds (>5 mm/s). In previous work, we used a model that combined underdamped flow and convection–diffusion oxygen transport to successfully explain a host of tissue-oxygen measurements (Kim et al., 2013; Ress et al., 2009).

Here, we extend our mathematical framework to interpret the BOLD signal for short stimulation, the HRF. The new “arterial impulse” model includes only CBF and CMRO₂ responses as drivers of the BOLD HRF; it excludes venous CBV changes based on the plethora of recent experimental findings.

We utilize a linear-network model to model the underdamped CBF response created by the prompt arterial vasodilation in terms of energy exchange between the kinetic energy of flow and the stored energy of downstream venous compliance. Although venous CBV changes in the cortical parenchyma have not been observed following short periods of activation, the compliance, which has been well documented experimentally (Binzoni et al., 2000; Romney and Lewanczuk, 2001), could be manifest downstream in larger venous vessels such as the sinuses. A stereotypical parametric temporal form is assumed for the CMRO₂ response.

The CBF and CMRO₂ are coupled to a spatiotemporal oxygen-transport model that include the mechanisms of blood flow, hemoglobin dissociation, and transmural oxygen diffusion to produce longitudinal profiles of oxygen concentration in capillaries. Because the BOLD signal is dominantly driven by venous-compartment oxygen-concentration changes, we also include flow and hemoglobin-dissociation effects in the venous compartment. Thus, we predict the longitudinal profiles of oxygen concentration in both capillary and venous compartments, which are then related to the HRF, including both intravascular and extravascular BOLD effects.

The arterial impulse model is distinguished from the balloon models (Buxton and Frank, 1997; Buxton et al., 2004; Buxton et al., 1998; Griffeth and Buxton, 2011; Zheng et al., 2005; Zheng et al., 2002) in multiple ways. First, it describes the short-stimulation HRF with experimentally observed (Drew et al., 2011; Fernandez-Klett et al., 2010; Hillman et al., 2007; Itoh and Suzuki, 2012; Vazquez et al., 2010) dynamics:

prompt arterial dilation without venous volume change. In contrast, the balloon model's venous vasodilation is only observed in consequence to very long stimulation periods. Second, our model utilizes 1-D continuum dynamics for oxygen dissociation, diffusion, and flow in capillary and vein, thus providing details of the longitudinal profiles (Fig. 1A); the balloon model uses a compartmental, spatially constant oxygen saturation (SO₂) approximation for capillary and vein (Fig. 1B). Third, our model provides a simpler and more linear interpretation of the HRF than balloon models, in which most non-linearity comes from non-linear venous inflation (Buxton et al., 2004; Buxton et al., 1998; Griffeth and Buxton, 2011). The absence of the putative venous inflation in the arterial impulse model results in an offset-linear relationship between CBF and CMRO₂ responses that is consistent with the observed non-linearity between the BOLD response and neural activity (Pfeuffer et al., 2003; Vazquez and Noll, 1998). Fourth, our model postulates independent CBF and CMRO₂ response kernels driven by the neural response. Most previous models assume a fixed ratio of CBF to CMRO₂ response. Finally, the modified balloon model assumes a temporal delay between CBF and CMRO₂ responses to obtain the observed initial delay in the HRF (Buxton et al., 2004); no physiological mechanism is provided for this delay. In our model, mass balance of the longitudinally resolves system links these responses without further assumption.

We test the arterial impulse model against measurements of the BOLD HRF in human visual cortex evoked by brief stimulation; these measurements use high-resolution fMRI to avoid contamination from large pial blood vessels. The model provides excellent fits to the measured HRFs, and quantifies how fMRI measurements correspond to competition between CBF and CMRO₂ for brief neural activation, offering a simpler, more linear theoretical interpretation for the BOLD HRF.

Materials and methods

BOLD signal

The basis of BOLD contrast is the transient phase dispersion of water proton spins by distortion of the local magnetic field (Ogawa et al., 1993). This distortion is mainly produced by the dominant concentration of deoxygenated hemoglobin (Hb) in parenchymal brain tissues such as cortical gray matter. In the absence of experimental neural activation, this distortion creates a relatively smaller MR signal. Contrast is primarily driven by transient CBF changes that have two effects. First, inflowing arterial blood replaces deoxygenated Hb with oxygenated Hb, reducing phase dispersion and thereby increasing the MR signal. Second, the increase in blood volume displaces extravascular fluid, causing a net decrease in MR signal. Griffeth and Buxton (2011) recently developed a BOLD signal equation based on magnetization components from three intravascular compartments (artery, capillary, and vein) and their associated extravascular compartments. The BOLD signal thereby depended on changes in SO₂ and CBV in each intravascular compartment. For the short-stimulation regime, we simplified their results, based on recent experimental findings, by neglecting volume changes in capillaries and veins. BOLD contrast evoked by arterial changes in oxygen concentration and volume can also be neglected for two reasons. First, arterial blood will have little direct effect on BOLD contrast because its SO₂ is relatively high (≈ 90%) (Vovenko, 1999), and its magnetic susceptibility is similar to that of extravascular tissue. Second, arterial CBV increases promptly when neural activity occurs. For short stimulation experiments, these prompt CBV effects may lead to a small increase in MR signal because highly saturated arterial blood generates slightly more signal than the extravascular fluid (Griffeth and Buxton, 2011; Spees et al., 2001). However, such prompt effects will have little impact on the full time-scale of the HRF. Moreover, it has been reported that arterial contribution to the BOLD signal is minimal at 3 T (Uludag et al., 2009). Altogether, we conclude that arterial CBV effects will be brief and small, and can therefore be neglected.

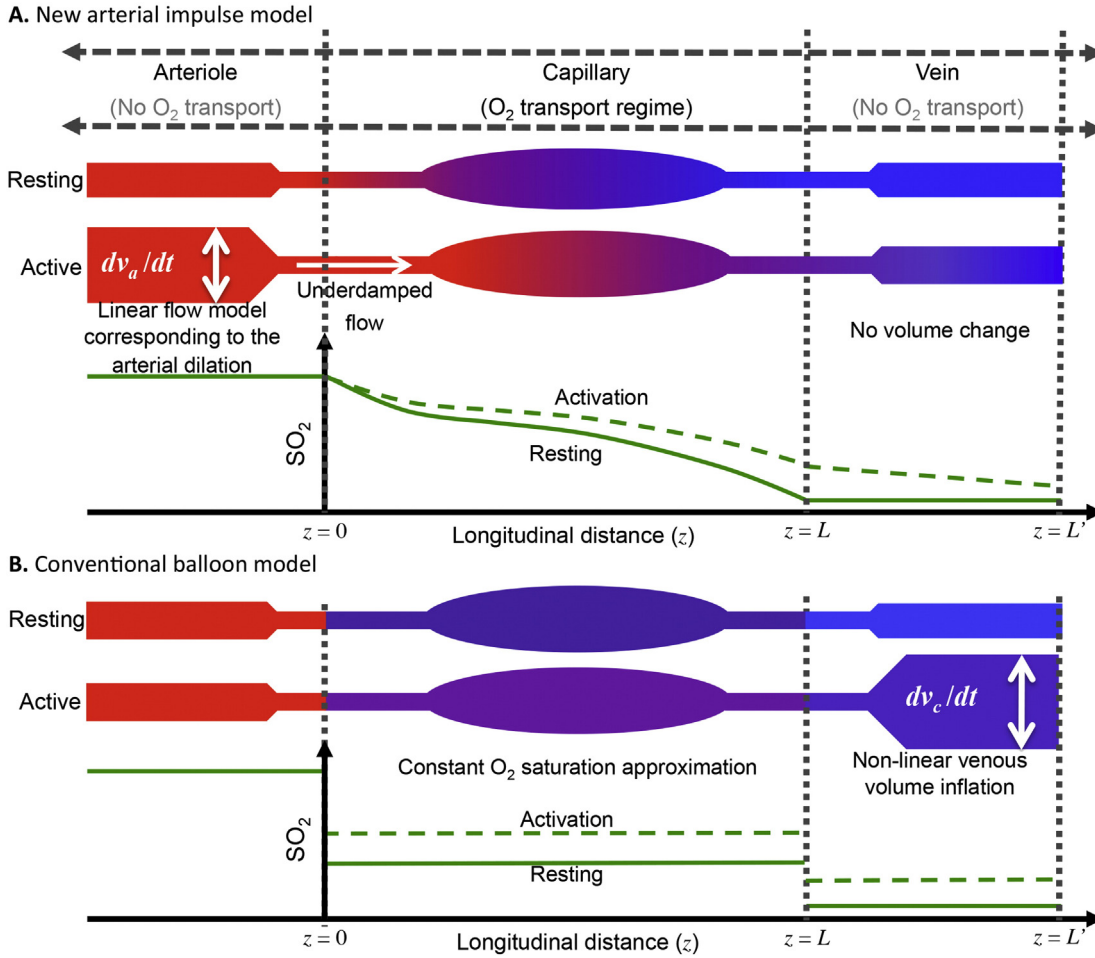


Fig. 1. Schematic of longitudinal SO_2 changes for activation and resting states with corresponding longitudinal SO_2 profiles for (A) arterial model, (B) balloon model; solid green line for resting, dotted green line for activation.

Under these assumptions, the BOLD contrast, the relative change in MR signal, δS , is now only a function of the SO_2 change in the capillary and venous compartments, and each compartment has intravascular and extravascular components:

$$\delta S = \frac{\varepsilon v_I}{1 - v_I + \varepsilon v_I} \exp(-TE \cdot \Delta R_{2I}^*) + \frac{1}{1 + \frac{\varepsilon v_I}{1 - v_I}} \exp(-TE \cdot \Delta R_{2E}^*) - 1, \quad (1)$$

where ε is the ratio of resting intravascular signal to extravascular signal, v is blood volume fraction, and subscripts I and E represent intravascular and extravascular. (See Table 1 for parameter values used and their references, and Appendix A for details of the derivation.)

Our oxygen transport model is spatially resolved, so we need to make assumptions about the gross distribution of oxygen transport within the vasculature. For simplicity, we assume that transport occurs only in capillaries, so oxygen saturation is constant in all of the arterial vasculature, then decreases through the capillaries by oxygen transport into tissue (Fig. 1A). We assume that there is no transmural oxygen transport in the veins (Tsai et al., 2003; Vovenko, 1999), so the baseline venous oxygen saturation is constant.

We assume a uniform cylindrical geometry for the capillary and vein, and finely grid their lengths. In the capillary, we use differential mass balance, including the processes of blood flow, hemoglobin oxygen dissociation, and oxygen diffusion into extravascular tissue, to obtain a continuous SO_2 spatial profile using a finite-difference method (FDM, details

below). The longitudinal profile in the venous compartment is calculated in a similar fashion, but neglecting diffusive transport of oxygen.

Previous models have neglected the longitudinal profile of oxygen concentration within the microvasculature (Buxton et al., 2004; Griffeth and Buxton, 2011). To deal with the spatially dependent oxygen saturation, the BOLD signal equation can be written as the sum of spatial averages (Kim and Ogawa, 2012) over four compartments:

$$\frac{\Delta S(t)}{S} = \delta S_{Ic}(t) + \delta S_{Iv}(t) + \delta S_{Ec}(t) + \delta S_{Ev}(t) - 1, \quad (2)$$

where subscripts c and v represent capillary and vein.

The first term on the right side of the equation represents the intravascular signal change in capillaries:

$$\delta S_{Ic}(t) = \int_{z=0}^L \frac{\varepsilon_c(z) v_c}{1 - v_c + \varepsilon_c v_c} \exp(-TE \cdot \Delta R_{2c}^*(z, t)) dz. \quad (3)$$

Here, the intravascular capillary transverse relaxation rate is:

$$\Delta R_{2Ic}^*(z, t) = C_c^* \left\{ (1 - SO_{2, c1}(z, t))^2 - (1 - SO_{2, c0}(z))^2 \right\}, \quad (4)$$

where C^* is an empirical constant (Griffeth and Buxton, 2011; Zhao et al., 2007). Subscripts 0 and 1 denote resting and activation, respectively. The

Table 1
Steady-state and BOLD signal parameters.

Description	Values	Reference
Oxygen extraction fraction at steady state	0.428	Ito et al. (2004) and Vovenko (1999)
Initial erythrocyte concentration in steady state, Q_{i0} (mmol/L)	8.56	Vovenko (1999)
Diffusivity (mm^2/s)	$1.6\text{E}-5$	Clark et al. (1978)
Diffusion rate constant	80	Clark et al. (1978), Tsai et al. (2003) and Vovenko (1999)
Steady-state CMRO_2 , Γ_0 (mmol/L/s)	0.081	Kim et al. (2013) and Lenigerfollert (1977)
Steady-state CBF, U_0 (mm/s)	0.7	Kim et al. (2013) and Nguyen et al. (2011)
Initial transmural gradient, σ	0.1	Kim et al. (2013) and Vovenko (1999)
Capillary volume fraction	0.4	Weber et al. (2008)
Vein volume fraction	0.4	Weber et al. (2008)
Effective CBV fraction	0.014	Cassot et al. (2006) and Vovenko (1999)
Hematocrit (capillary), Ht_c	0.2	Lecoq et al. (2011)
Hematocrit (vein), Ht_v	0.44	Gustard et al. (2003)
Resting extravascular rate of signal decay, R_{2E}^* (s^{-1})	25.1	Perthen et al. (2008)
Susceptibility of fully deoxygenated blood, $\Delta\chi$	$2.64\text{E}-7$	Spees et al. (2001)
Blood saturation for equal tissue-blood susceptibility, $\text{SO}_{2,\text{ref}}$	0.95	Spees et al. (2001)
Constant term for vein, C_v^* (s^{-1})	174.7	Zhao et al. (2007)
Constant term for vein, A_v^* (s^{-1})	21.2	Zhao et al. (2007)
Constant term for capillary, C_c^* (s^{-1})	142.7	Zhao et al. (2007)
Constant term for capillary, A_c^* (s^{-1})	19.7	Zhao et al. (2007)

term $\varepsilon_c(z)$ is the ratio of resting intravascular to extravascular signals in capillaries as a function of the longitudinal direction:

$$\varepsilon_c(z) = \frac{S_{c,0}}{S_{E,0}} = \lambda \frac{\exp[-TE \cdot \{A_c^* + C_c^* \cdot (1 - \text{SO}_{2,c0}(z))\}]}{\exp(-TE \cdot R_{2E}^*)}. \quad (5)$$

The second term in Eq. (2) is the intravascular signal change in veins with spatial averaging given by the quantity:

$$\delta S_{IV}(t) = \int_{z=L}^{L'} \frac{\varepsilon_v V_v}{1 - v_v + \varepsilon_v V_v} \exp(-TE \cdot \Delta R_{2IV}^*(z, t)) dz, \quad (6)$$

where

$$\Delta R_{2IV}^*(z, t) = C_v^* \left\{ (1 - \text{SO}_{2,v1}(z, t))^2 - (1 - \text{SO}_{2,v0}(z))^2 \right\}. \quad (7)$$

We assume that the resting venous oxygen saturation is spatially constant at its value at the distal end of the capillary, $\text{SO}_{2,v0}(z) = \text{SO}_{2,c0}(z = L)$, so the ratio of resting intravascular to extravascular signals in the vein, ε_v is also spatially constant.

The third and forth terms in Eq. (2) are the extravascular signal changes in capillaries and veins, which have forms similar to the intravascular terms:

$$\delta S_{Ec}(t) = \int_{z=0}^L \frac{1}{1 + \frac{\varepsilon_c(z) V_c}{1 - v_c}} \exp(-TE \cdot \Delta R_{2Ec}^*(z, t)) dz, \quad \text{and} \quad (8)$$

$$\delta S_{Ev}(t) = \int_{z=L}^{L'} \frac{1}{1 + \frac{\varepsilon_v V_v}{1 - v_v}} \exp(-TE \cdot \Delta R_{2Ev}^*(z, t)) dz. \quad (9)$$

Here,

$$\Delta R_{2Ec}^*(z, t) = 0.04(\Delta\chi \cdot Ht_c \cdot \gamma \cdot B_0)^2 \times \left\{ (\text{SO}_{2,\text{ref}} - \text{SO}_{2,c1}(z, t))^2 - (\text{SO}_{2,\text{ref}} - \text{SO}_{2,c0}(z))^2 \right\}, \quad (10)$$

$$\Delta R_{2Ev}^*(z, t) = \frac{4\pi}{3} \Delta\chi \cdot Ht_v \cdot \gamma \cdot B_0 (\text{SO}_{2,v1}(z, t) - \text{SO}_{2,v0}(z)), \quad (11)$$

where $\Delta\chi$ is the susceptibility of fully deoxygenated blood, Ht is the hematocrit, γ is the gyromagnetic ratio of protons, B_0 is the magnetic field strength, $\text{SO}_{2,\text{ref}}$ is the oxygen saturation for equal blood-tissue susceptibility.

CBF response

Recent experiments indicate that brief brain activation produces a rapid wave of vasodilation starting from the activated brain region and extending to the superficial pial arteries (Devor et al., 2011; Itoh and Suzuki, 2012; Tian et al., 2010). Therefore, the flow response spans two fluid-behavior regimes: upstream transient CBF in arteries and corresponding downstream CBF in the microvasculature. In pial arteries, relatively larger vessel diameters ($>200 \mu\text{m}$) and high flow speeds ($>20 \text{ mm/s}$) make inertial effects significant (Kim et al., 2013; Ress et al., 2009). So, we model the upstream flow response using a lumped linear network that includes inertial effects. Prompt arterial vasodilation creates an impulsive resistance decrease, yielding the flow impulse-response:

$$U_{FEW}(t) = U_1 \exp(-t/\tau) \sin(2\pi f t), \quad (12)$$

with frequency f , damping time τ , and amplitude U_1 . The underdamped oscillatory response corresponds to exchange between kinetic (inertial) energy and compliant energy distributed through the downstream venous vasculature, resulting in an oscillatory flow response. This linear model provides a biomechanical basis for a damped sinusoidal flow response.

Because of the small vessel diameters and slow flow speeds, the CBF in capillaries should exhibit “creeping” flow that is driven linearly by the upstream CBF response (U_{FEW}), modulated by a viscous friction. Therefore, the CBF response in the capillaries should have the same underdamped form as in the upstream vasculature.

CMRO₂ response

We assume an analytic form for the CMRO₂ as an input to our convection–diffusion transport model. The CMRO₂ response shows how much oxygen diffuses into surrounding tissues evoked by neural activity. We assume spatially uniform oxygen uptake to avoid complexity. Prompt increases and relatively slow decays in the CMRO₂ temporal response were observed in previous experiments (Masamoto and

Tanishita, 2009; Vazquez et al., 2010), with substantial variability among the observed responses. So, we use a gamma-variate function to characterize various CMRO₂ responses:

$$\Gamma_g(t) = \frac{\Gamma_1}{\eta N} t^{\xi-1} \exp\left(-\frac{t}{\eta}\right), \quad (13)$$

where N is a normalization constant, damping time is η , shape coefficient ξ , and amplitude Γ_1 . The damping time mostly characterizes the decay of the transient CMRO₂ change, while the shape coefficient principally affects its rise time.

Relating CBF and CMRO₂ to the HRF

We estimate neural activity as a rectangular pulse inducing transient responses in both CBF and CMRO₂. Accordingly, convolution with the rectangular pulse models the full CBF and CMRO₂ responses corresponding to the neural activity.

Capillary oxygen transport

We model the aggregate behavior of capillary transport using a single cylinder consisting of three radial compartments (erythrocyte, plasma and extravascular tissue, see Fig. 2). Mass balance includes four components: convection, dissociation, diffusion, and CMRO₂. First, convection corresponds to the blood flow along the vessel (z-axis), and this occurs in both erythrocyte and plasma compartments. Second, hemoglobin-bound oxygen in the erythrocyte compartment dissociates into the plasma compartment, which is calculated using a quadratic fit to the Hill equation (Sharan et al., 1989). Third, oxygen diffuses from the plasma to the extravascular tissue. Fourth, the CMRO₂ response is modeled as spatially uniform oxygen uptake from the extravascular compartment. The combination of these dynamics produces a set of three partial-differential equations, one for each radial compartment, which can be solved numerically; see Appendix B for details. Resting flow speed in the capillary was assumed to be 0.7 mm/s; cylinder length was determined from resting oxygen mass balance to be 842 μm (Appendix B).

Venous oxygen transport

The venous geometry is modeled as a second cylinder extending beyond the capillary. Because we assume no venous oxygen diffusion, mass balance includes only two components: convection and dissociation. Venous flow speed is assumed to be 2.5 mm/s (Santisakultarm et al., 2012). Cylinder length was approximated on order of the gray-matter thickness (Fischl and Dale, 2000; Ress et al., 2007), ~ 2 mm.

Measurement of the BOLD HRF

The BOLD HRF is evoked in 7 subjects and 9 sessions using 2-s presentations of 4-Hz flickering dots covering the full visual field, followed by 26-s inter-stimulus intervals (Fig. 3A). Subjects perform a fixation-dot task throughout to encourage stable fixation and visual attention. High-resolution (0.9-mm voxels) fMRI data are obtained using a 3T GE Signa scanner. Acquisition (1.5 s/volume) uses a 2-shot spiral trajectory on 8 slices (90-mm FOV, 25-ms TE, 750-ms TR) oriented normally to the calcarine sulcus in posterior occipital cortex, to cover portions of visual areas V1–3. We average the time series from a set of strongly responding voxels (top 50% of contrast-to-noise-ratio), to obtain the averaged HRF for two regions-of-interest (ROIs): striate visual cortex (V1) and extrastriate cortex (V2 and V3 combined, termed V23). We separate these ROIs because substantial differences in their cytoarchitecture could potentially lead to different HRFs. Each session produces 72–85 HRF measurements, depending on the number of runs collected. Our high spatial resolution allows us to use only fMRI voxels that are fully

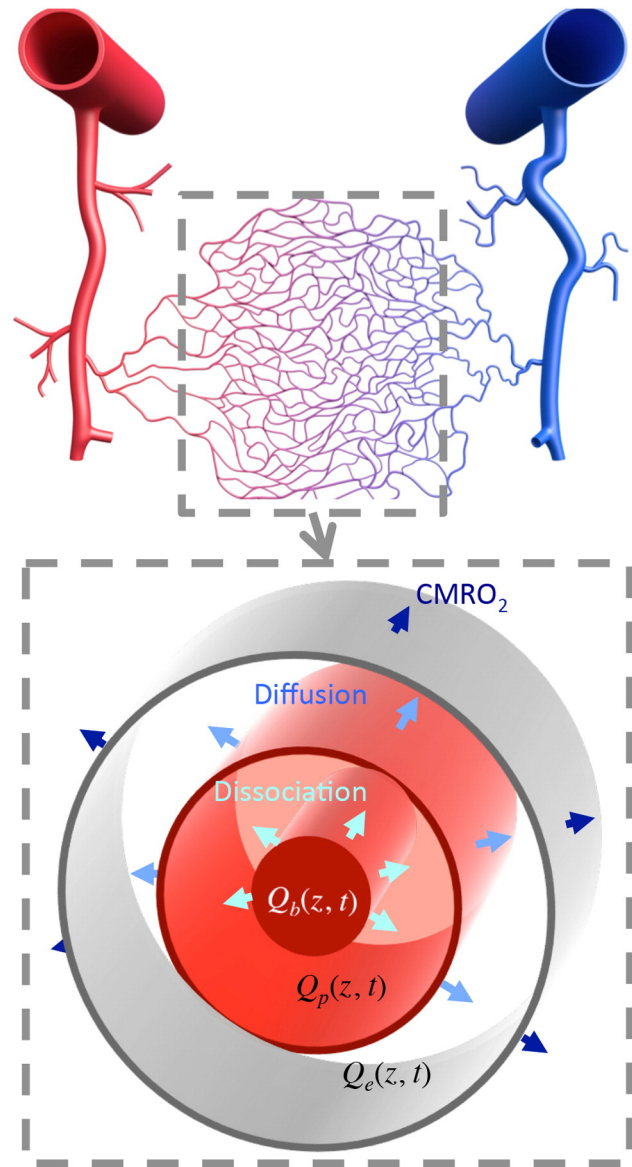


Fig. 2. (Upper) Schematic of a cortical vascular network; the gray dotted line shows the capillary bed when oxygen transport mainly occurs. (Lower) Schematic of the cylindrical geometry for the oxygen transport model with three radial compartments (erythrocyte, plasma and extravascular tissue) that is used to model oxygen dissociation, diffusion, and oxygen demands in capillaries.

embedded in the gray matter to minimize contamination from large pial vessels.

Fitting model to measurements

The transient mass balance equations for the cylindrical geometries in both capillary and vein are solved using a FDM. We finely grid the length of the cylinders, and approximate derivatives as centered differences. The resulting gridded system of algebraic equations is then solved for each time step to obtain the temporal evolution of the longitudinal oxygen spatial profile in all compartments. To obtain an initial set of longitudinal profiles for the capillary compartment, we use the analytical solutions for steady-state mass balance (Appendix B).

These spatial profiles are then longitudinally integrated, Eqs. (3)–(11), and fit to measurements of the BOLD response by adjusting the six CBF and CMRO₂ parameters in Eqs. (12)–(13). The six parameters are initially adjusted manually to approximately match each measured HRF. From these initial parameters, we use non-linear optimization to adjust these

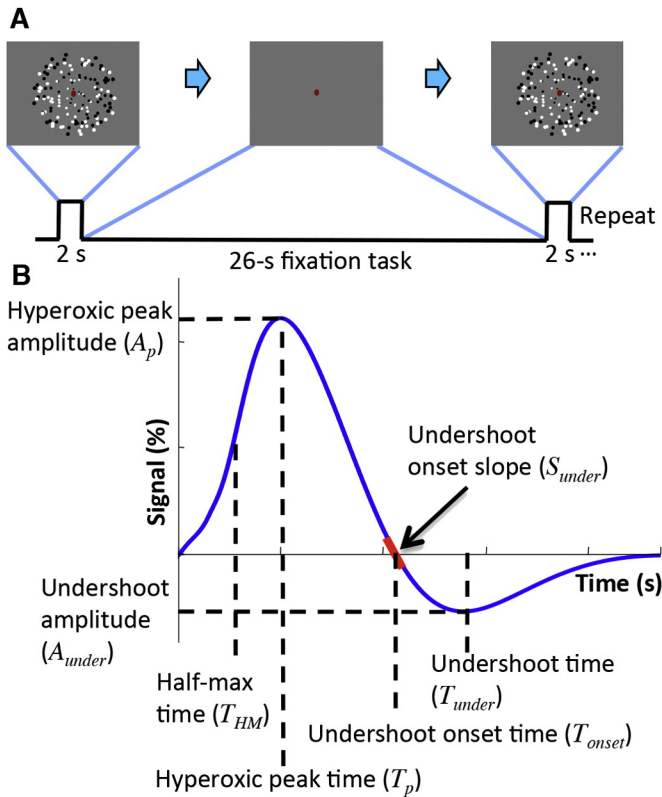


Fig. 3. (A) Visual stimulus for BOLD HRF measurement in cerebral cortex. (B) Temporal and amplitude parameters used to characterize the HRF and corresponding CBF and CMRO₂ responses.

parameters to minimize the RMS deviation between the theoretical fit and the measured HRF. Fits are deemed successful when the ratio of mean deviation of the fit to the experimental standard error is <1 .

This procedure is subject to ambiguity because of local minima within the highly complex six-parameter feature space, but the initial manual adjustment helped substantially by providing a physically reasonable starting point. We also found similar results using a “default” set of initial parameters. Although there may be a plethora of possible good fits, we believe that this procedure provides parameters that well describe the HRF within the framework of our model.

Quasi-steady-state solution

To understand relationships between CBF and CMRO₂ responses, we derived a quasi-steady-state mathematical form at the peak HRF where the temporal derivatives are all approximately zero (Appendix B). At the HRF peak, the CBF and CMRO₂ response can be expressed as sums of resting and activation response: $U_{act} = U_0 + \Delta U$, $\Gamma_{act} = \Gamma_0 + \Delta\Gamma$. The result yields an offset linear relationship form between changes in transient CBF (ΔU) and CMRO₂ ($\Delta\Gamma$) responses:

$$\Delta U = \frac{L}{S} \Delta\Gamma + \frac{L}{S} \Gamma_0 - U_0, \quad (14)$$

where S is a complex parameter that depends on transient OEF, as well as many of the fixed resting-state parameters of flow, hemoglobin oxygen dissociation, and diffusion. We also obtain a reciprocal relationship between the CBF-to-CMRO₂ response amplitude ratio, $n = \Delta U / \Delta\Gamma$, and the CMRO₂ response:

$$n = \left(\frac{L}{S} \Gamma_0 - U_0 \right) \frac{1}{\Delta\Gamma} + \frac{L}{S}. \quad (15)$$

Analysis of the model HRF

We investigate correlations between parameters of the HRF, and corresponding CBF and CMRO₂ responses. We define seven parameters for HRF, CBF and CMRO₂ responses (Fig. 3B). For the initial delay, a temporal parameter (T_{HM}) is obtained at the half-max of the peak. For the peak of the initial hyperoxic response, we obtain amplitude (A_p) and time (T_p) parameters. For the undershoot, we obtain amplitude (A_{under}) and time (T_{under}) parameters corresponding to the maximum negative response following the hyperoxic peak. Undershoot-onset-slope (S_{onset}) and time (T_{onset}) are obtained at the zero crossing of the response after the hyperoxic peak. For successful fits, we examine correlations between parameters and evaluate variance explained by linear relationships, R^2 .

Results

Characteristics of the arterial impulse model

Starting from analytic resting solutions, the spatiotemporal evolution of the oxygen responses are calculated in capillary and vein. The largest variation of the oxygen saturation ($\sim 10\%$ of oxygen extraction fraction) is predicted at the distal end of the capillary. This change in oxygen extraction fraction (OEF) by activation agrees with previous reports (Buxton, 2013; Griffeth and Buxton, 2011; He and Yablonskiy, 2007). The SO_2 and ΔSO_2 vary non-linearly from the proximal end of the capillary to distal end of the vein. In absolute terms, activation creates fairly small changes in oxygen saturation (Fig. 4A), but the relative changes are substantial (Fig. 4B). Profiles are shown at six different time points, which are keyed to colored vertical lines along the corresponding volume integrated BOLD response (Fig. 4A, inset). The capillary dynamics are fairly complex. As flow rises initially, relative oxygen saturation rises and develops curvature, then sags downward before inverting to become the undershoot with reversed curvature. In the venous compartment, longitudinal profiles are more linear with strong correlations between temporal and spatial gradients. At onset, peak, and undershoot times, the spatial gradients are relatively flat, while at times of strong temporal change, the gradients are relatively large; this is a manifestation of transient convective transport through this compartment. Accordingly, there is a temporal lag between the proximal and distal ends of the SO_2 response in the vein (Fig. 4C). The substantial ΔSO_2 variation along the vessel length in both capillary and vein is summarized throughout time course of the HRF (Fig. 4D).

Model fits to the measurements

We aimed to obtain 18 HRF measurements from two ROIs in nine sessions (from seven subjects), but one ROI in one session did not yield useful information because of the orientation of the slice prescription, so we present results for 17 HRF measurements. Analysis of BOLD HRF parameters shows no significant differences between V1 and V23, and between V2 and V3, and their corresponding CBF and CMRO₂ response predictions.

The model estimates the contribution to the BOLD signal for four compartments: intra- and extravascular vein and capillary. There is little temporal variation in the relative contributions of these compartments, but the effects are clearest at the hyperoxic peak and the undershoot. The largest contribution ($75.8 \pm 1.1\%$) is from the extravascular venous compartment, followed by intravascular vein ($16 \pm 0.3\%$), intravascular capillary ($5.1 \pm 0.9\%$), and extravascular capillary ($3.1 \pm 0.3\%$).

Most of the measured BOLD HRFs show stereotypical temporal response patterns consisting of initial latency, hyperoxic peak, and undershoot (Fig. 5A). Overall, the arterial impulse model (Fig. 5, red) successfully fit the measurements (blue), but the fit quality is highest during the hyperoxic peak, and tends to deteriorate somewhat during the undershoot.

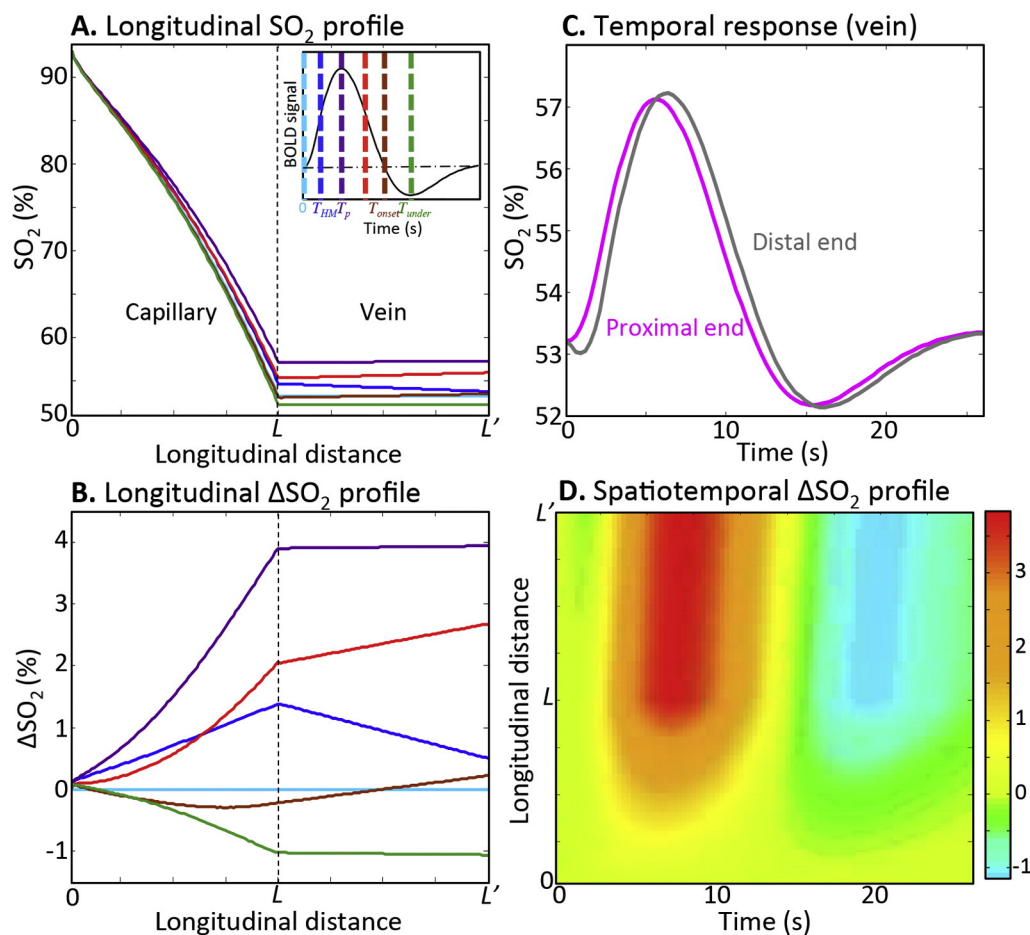


Fig. 4. Characteristics of the arterial impulse model. Examples of longitudinal (A) SO_2 and (B) ΔSO_2 profiles for six time points in capillary and vein: resting (light blue), initial half-maximum (blue), HRF peak (purple), trailing half-maximum (red), undershoot-onset (brown), undershoot peak (green). Inset shows these time points on a stereotypical HRF. (C) Examples of SO_2 time course for distal (gray) and proximal (magenta) ends of the vein. (D) An example of spatiotemporal color contour map for ΔSO_2 in capillary and vein.

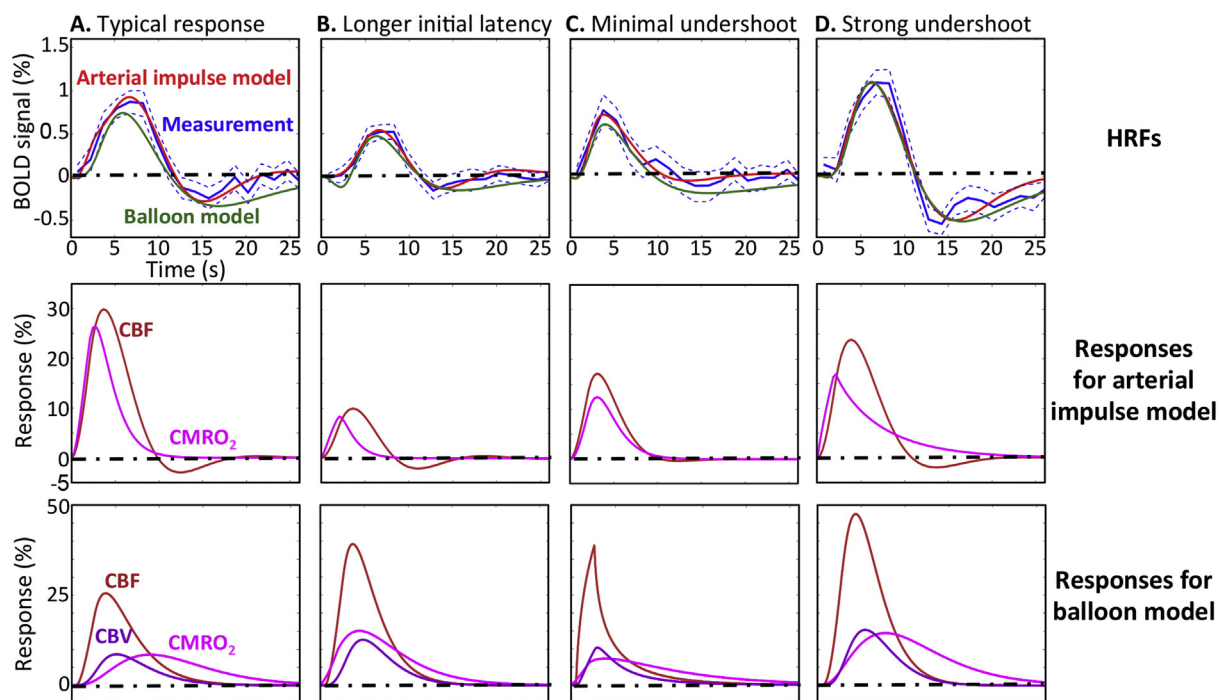


Fig. 5. (Upper) Examples of fits from arterial impulse model (red), and balloon model (green) to measured BOLD responses (blue); dotted blue lines show 68% confidence intervals. (Middle) The CBF (orange) and $CMRO_2$ (magenta) responses predicted by the arterial impulse model. (Lower) CBF, $CMRO_2$, and CBV (purple) responses predicted by the balloon model.

The model explains the HRF as competition between CBF (orange) and CMRO₂ (magenta), shown in the middle panels of Fig. 5. At the onset of the HRF, CMRO₂ immediately increases followed by the CBF; this competition creates the initial latency. Then, the HRF starts increasing as the CBF-driven oxygenation exceeds the diffusion-mediated CMRO₂ demand; this is the transient “neurovascular uncoupling.” Differences in the timing and magnitude of the uncoupling create the variability in the initial latency. For example, one HRF exhibiting long initial latency ($T_{HM} = 4.1$ s, Fig. 5B) is predicted to correspond to a relatively prompt increase in CMRO₂ compared with the CBF response. In contrast, an HRF with short initial latency ($T_{HM} = 2.1$ s, Fig. 5C) is predicted to correspond to slower CMRO₂ responses. Generally, the CBF response continues to increase after the CMRO₂ peak, but the HRF peaks significantly later than the CBF peak (mean delay 2.1 s, $p < 0.01$). This delay corresponds to the longitudinal transport of oxygen along the length of the vessels, driven by the corresponding CBF and CMRO₂ responses.

We observe significant undershoot amplitudes (A_{under}) in all of the HRFs (mean amplitude $0.24 \pm 0.13\%$; $p < 0.01$). However, there are substantial session-to-session variations of the undershoot amplitude. The model fits these variations well with combinations of CBF oscillation and slow CMRO₂ recovery. In the typical HRF (Fig. 5A), the BOLD undershoot is largely driven by CBF undershoot, while HRFs with small undershoot (e.g., Fig. 5C) are predicted to correspond to small CBF undershoot. On the other hand, a combination of CBF undershoot and slow CMRO₂ decay can form HRFs exhibiting strong undershoot with slow recovery to baseline (Fig. 5D).

We also fit the measured HRFs using the balloon model (Fig. 5, upper panels, green curves; see Appendix C for details). The corresponding CBF, CMRO₂ and CBV (lower panels) show the reliance of this model on venous dilation effects to match both early- and late-time dynamics of the HRF. Overall, the balloon model did not perform as well as the new arterial impulse model; successful fits were obtained for only 10 of the 17 measured HRFs. We consistently observe that the balloon model fails to fit the varied late-time behaviors of the measurements.

Fit parameters are summarized in Table 2. There are substantial session-to-session variations for both CBF and CMRO₂ peak amplitudes (A_p), but the variability is within the range of previous measurements (Feng et al., 2004; Griffeth and Buxton, 2011; Huo et al., 2014; Ito et al., 2005). The predicted oscillation frequency of the HRF is fairly stable among the measurements (0.052 ± 0.009 Hz), consistent with previous extravascular oxygen measurements and modeling (Kim et al., 2013; Thompson et al., 2003) (0.064 ± 0.016 Hz). Damping times of the model fits were somewhat more variable (3.7 ± 0.8 s), and are substantially shorter and less variable than those observed for the tissue oxygen data (11 ± 11 s), which exhibited much more undershoot and oscillation.

We normalize all measurement time series, their model fits, and corresponding CBF and CMRO₂ by their maximum values to compare response waveforms across sessions (Fig. 6). Experimentally, we observe substantial session-to-session variations among the HRF time courses. In general, variability is relatively small at early times, and grows larger after the hyperoxic peak. The normalized-model HRFs again show good correspondence to the measurements (Fig. 6B). Normalized CBF responses (Fig. 6C) follow a similar pattern as the HRFs: similar shapes before the hyperoxic peak, and much larger session-to-session variations after the peak. These features correspond to the stability of the oscillation frequency, and the session-to-session variability of the flow damping parameter. Normalized CMRO₂ responses (Fig. 6D) generally

exhibit a prompt increase to their peak, followed by slow decay back to baseline, but show much greater variability throughout their time courses than the predicted CBF responses.

The consistent early-time behavior of the HRF is manifest in several ways. First, the time-to-peak ($T_{p,HRF}$) of the HRFs is relatively stable at 5.9 ± 1.0 s. The model predicts that the early time behavior of both CBF and CMRO₂ responses are correspondingly consistent across HRFs (Figs. 6C, D). Moreover, the model shows strong and significant relationships between the peak amplitudes. There is a positive relationship between the CBF and CMRO₂ peak amplitudes ($R^2 = 0.94$, slope = 0.95, $p < 0.01$; Fig. 7A). This offset linear relationship is consistent with a strongly nonlinear relationship between the CBF-to-CMRO₂ amplitude ratio (n) and the CMRO₂ amplitude ($A_{p,CMRO_2}$); the range of n in our data is 1–4 (Fig. 7B). Using the predicted peak CBF and CMRO₂ amplitudes, this nonlinear relationship can be very well fit by a simple reciprocal relationship; $n = a / A_{p,CMRO_2} + b$ (black line; $R^2 = 0.9$; Fig. 7B).

Both of these relationships are well explained by the quasi-steady-state limit of our model (Eqs. (14)–(15); Figs. 7C–D). The quasi-steady-state assumption only holds at the HRF peak (Fig. 7D inset). So, we use the full model to obtain corresponding CBF and CMRO₂ responses at the HRF peaks for all sessions (Figs. 7C–D, blue points), and compare them with CBF and CMRO₂ responses analytically obtained from the quasi-steady-state assumption (red points). Both of them show strong linear correlations between CBF and CMRO₂ responses (blue line: $R^2 = 0.93$, slope = 1.17, $p < 0.01$; red line: $R^2 = 0.82$, slope = 1.18, $p < 0.01$; Fig. 7C). For a set of the predicted CMRO₂ responses, the calculated CBF responses from Eq. (14) are similar to those from the full model, demonstrating the accuracy of quasi-steady-state approximation ($R^2 = 0.98$, root-mean-square error = 2.2%). Examining the dependence of response ratio n vs. CMRO₂ at the HRF peak, the full model (Fig. 7D, red points) and quasi-steady-state approximation (blue points) again show good agreement ($R^2 = 0.98$, RMSE = 0.32). Accordingly, the data thus confirm the reciprocal relationship between n and the CMRO₂ response from the full model (Fig. 7D, red line), which is very similar (RMSE = 0.15) to the quasi-steady state prediction (Eq. (15); Fig. 7D, blue line).

In contrast to the generally stereotypical early-time behavior, the HRF undershoot varies substantially among measurements. Despite this variability, there is a strong correlation between the HRF slope at undershoot onset ($S_{onset,HRF}$) and the corresponding undershoot amplitude ($R^2 = 0.84$, $p < 0.01$, slope = 2.1; Fig. 8A). In other words, the faster the decay of the hyperoxic peak, the greater the subsequent undershoot. Our model explains this behavior with the underdamped CBF response: both the predicted CBF undershoot amplitude ($A_{under,CBF}$) and its slope at undershoot onset ($S_{onset,CBF}$) show significant correlations with $S_{onset,HRF}$ (CBF undershoot amplitude: $p < 0.01$, $R^2 = 0.39$, slope = 9.7, Fig. 8B; CBF undershoot slope: $p < 0.01$, $R^2 = 0.58$, slope = 13.3, Fig. 8C). However, there is no significant correlation between HRF-undershoot amplitude and CBF-undershoot amplitude ($p = 0.23$; $R^2 = 0.10$; slope = 0.05, Fig. 8D).

Discussion

For over a decade, volume change in the venous compartment was considered a key feature for the BOLD HRF (Buxton et al., 2004; Buxton et al., 1998; Griffeth and Buxton, 2011; Mandeville et al., 1999; Obata et al., 2004). However, recent experiments using optical imaging techniques reported no significant change in venous CBV for brief neural

Table 2
Mean and standard deviations of fit parameters.

	τ (s)	f (Hz)	η (s)	ξ	T_p (s)	A_p (%)	T_{under} (s)	A_{under} (%)
HRF	3.7 ± 0.8	0.052 ± 0.009	2.4 ± 1.2	1.8 ± 0.5	5.9 ± 1.0	0.93 ± 0.22	15.5 ± 1.7	0.24 ± 0.13
CBF					3.7 ± 0.3	21.6 ± 10.5	13.7 ± 1.9	1.6 ± 0.9
CMRO ₂					3.0 ± 0.8	15.8 ± 10.8		

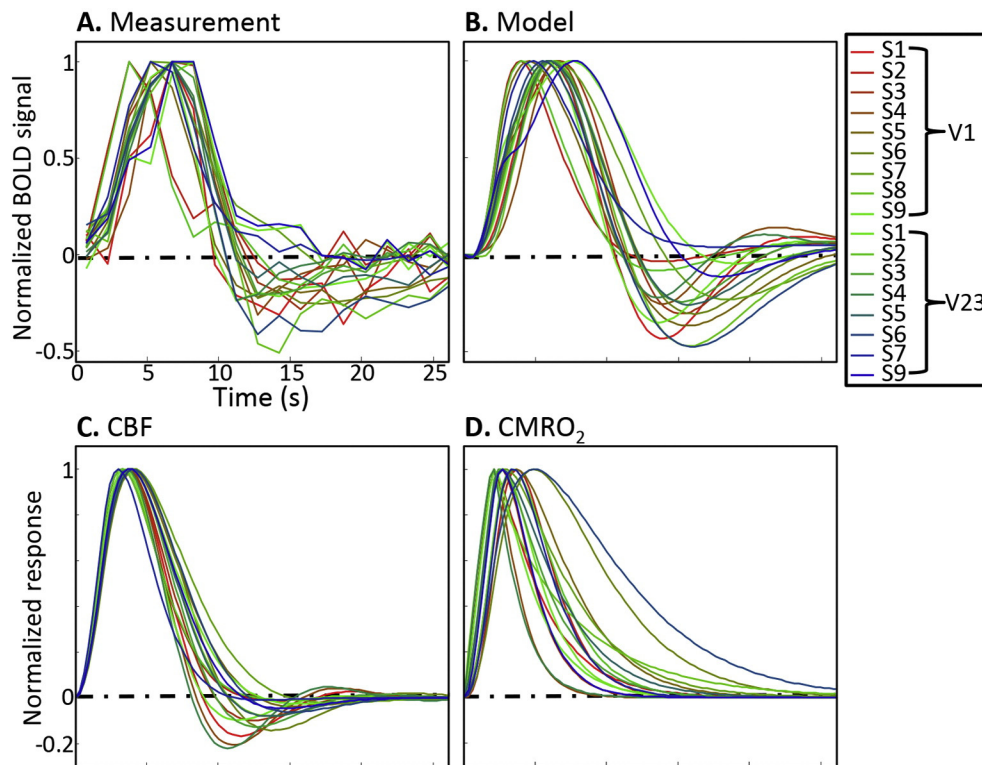


Fig. 6. Time series of (A) BOLD measurements, (B) models, with corresponding (C) CBF and (D) CMRO_2 , all normalized by their maximum values. Each colored line corresponds to a different HRF measurement. The comparison highlights the periods of temporal stability and variability among the HRFs.

activation. In fact, they observed strong and prompt volume changes in the arterial side. For example, Hillman et al. characterized the depth-resolved hemodynamic responses in individual arterioles and veins evoked by 4-s somatosensory stimulus using two-photon laser microscopy in rat gray matter. They found significant capillary hyperemia in the activated region, as well as prompt upstream arterial vasodilation. However, there was no significant volume change in the venous vasculature during neural activation (Hillman et al., 2007). Another two-photon imaging study produced hemodynamic responses by inducing brief seizure activity using pharmaceutical manipulation, and measured volume changes in corresponding pial arteries, penetrating arterioles, precapillary arterioles, and capillaries during neural activation (Fernandez-Klett et al., 2010). Both transient flow speed and volume changes were observed in all upstream arterial vessels, but there was no dilation in capillaries, which implied active flow control by upstream pial arteries and penetrating/precapillary arterioles. Pial arteries and veins also showed similar dynamics in optical measurements of vessel-diameter changes evoked by 20-s somatosensory stimulation in anesthetized rats (Vazquez et al., 2010). No dilation was seen in veins with $\sim 150\text{--}350\ \mu\text{m}$ diameter, while significant volume changes were found in arterioles ($\sim 80\text{--}130\ \mu\text{m}$ diameter). Drew et al. measured arteriolar and venular diameters for three different vibrissa stimulation durations in mice with 20-ms puffs of air (single puff, 10-s stimulation train with 50% duty cycle, and 30-s stimulation train) using two-photon laser microscopy. They found that brief stimulation led only to arterial dilation, while long stimulation periods produced large prompt arterial dilation followed by smaller gradual venous dilation (Drew et al., 2011). Recently, they also measured vessel dilations and corresponding CBF responses in awake, behaving rats, and reported fast arterial ($5.5 \pm 5.1\ \text{s}$) and slow venous ($25.1 \pm 17.9\ \text{s}$) time constants. These results also showed that the pial artery dilation evoked by locomotion had a linear relationship with the corresponding CBF response (Huo et al., 2014).

Here, we establish a biomechanical model that includes the hypothesis that prompt upstream arterial dilation is a key physiological mechanism for the HRF, and link this description to the BOLD signal to

formulate a new arterial impulse model. Measurements using high-resolution fMRI demonstrate the efficacy of the model.

The arterial impulse model has three longitudinal compartments (artery, capillary, and vein) to describe the physiology of the HRF. In the arterial compartment, the prompt dilation corresponding to neural activation generates an underdamped flow response that propagates to the downstream capillary and vein. In the capillary, we obtain longitudinal oxygen-saturation profiles by solving differential equations (with dissociation, convection, and diffusion dynamics) within three radial divisions (erythrocyte, plasma, and extravascular) driven by the upstream CBF response and local CMRO_2 demand. In the vein, there is no radial oxygen diffusion, but blood flow and oxygen dissociation combine to give longitudinal oxygen transport. The model links the arterial dilation and flow dynamics to oxygen transport within capillary and venous compartments, and thereby obtains the venous compartment oxygen saturation that has the greatest contribution ($\sim 90\%$) to the BOLD signal.

In this model, we considered both intravascular and extravascular contributions to the BOLD signal. Although intravascular venous and capillary volume fraction is small ($\sim 3.6\%$) (Ladurner et al., 1976; Phelps et al., 1979), the model shows a substantial intravascular contribution ($\sim 20\%$ of total BOLD response). This result is consistent with previous reports that intravascular signal change in blood, per unit volume, is more than an order of magnitude higher than that in extravascular tissue (Boxerman et al., 1995).

By appropriately neglecting venous volume effects, our model greatly simplifies the interpretation of BOLD HRF as a competition between oxygen supply (delivered by CBF) and demand (CMRO_2). Notably, there is an initial brief decoupling of CBF from CMRO_2 . The CMRO_2 response is always predicted to come first, which corresponds to oxygen demand from neural activity, followed by the CBF response that supplies oxygen and other metabolic substrates. For the first few seconds, the CMRO_2 responses are predicted in most measurements to be higher than the CBF responses, and the degree of this local decoupling determines the duration of the initial latency of the HRF. For example, there

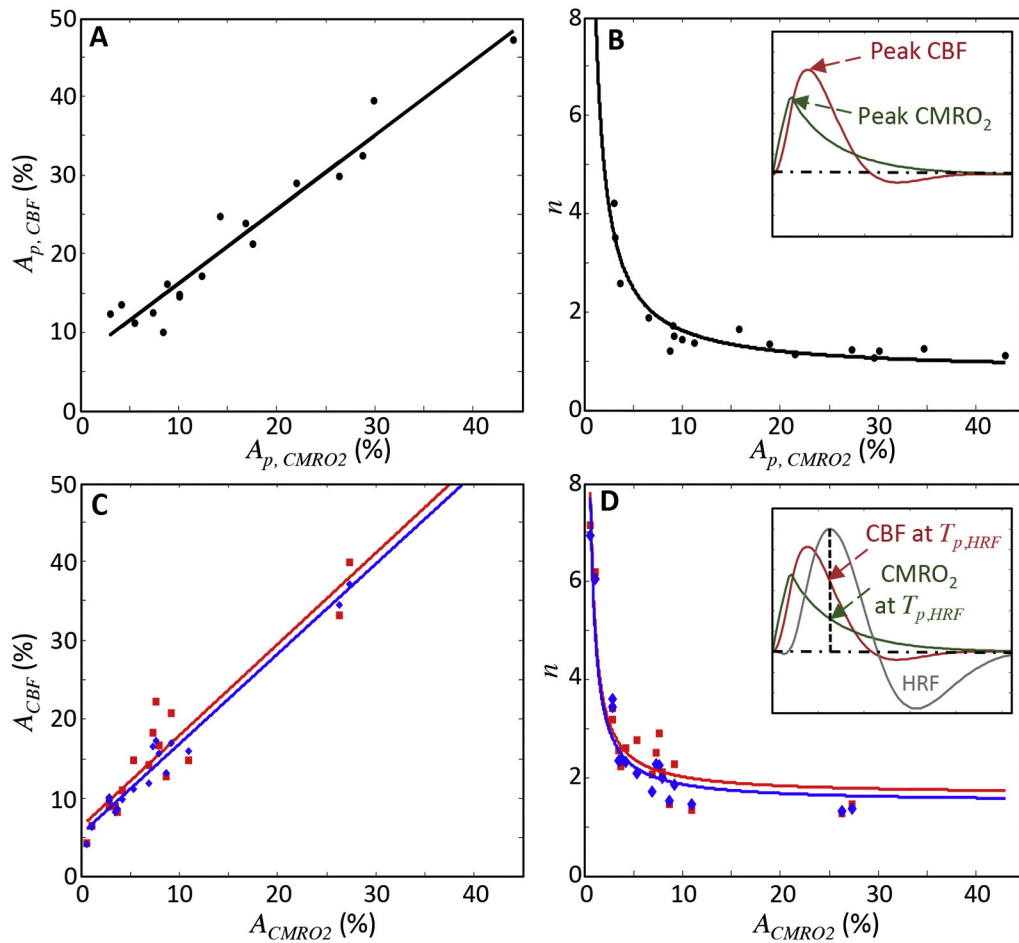


Fig. 7. (A–B) Correlations between peak CBF and peak CMRO₂ responses for the 17 HRFs; inset in (B) shows example of peak CBF and peak CMRO₂ corresponding to one data point. (C–D) Comparison of correlations between full model (blue) and quasi-steady-state approximation (red) at peak HRF; inset in (D) shows an example of the CBF and CMRO₂ responses at HRF peak for one data point.

is a long initial latency in Fig. 5B, which the model explains as CMRO₂ demand increasing faster than the CBF, while there is a minimal initial latency in Fig. 5C, which the model explains as greater temporal synchrony between the CMRO₂ and CBF responses.

After the CMRO₂ peak, the CBF response continues to increase, reaching its peak at ~3.8 s. Remarkably, the HRF peak, the most prominent feature of the BOLD HRF, occurs substantially later at 5.9 s. Our model explains this decoupling of BOLD response from metabolism as a convective response delay. Although arterial vasodilation follows the local transient neural activity, the consequent blood flow has momentum that will continue to provide more blood and oxygen in the microvascular network, producing the delayed CBF. Moreover, these blood-flow effects introduce different convective delays in the different compartments. In particular, the flow effect occurs latest in the venous compartment, thus producing the late peak of the HRF. As the blood flows through the compartments, it produces longitudinal gradients in oxygen saturation that must propagate fully to establish peak oxygen saturation at the HRF peak. The linear convective gradients are most clearly evident in the venous compartment because of the absence of transmural oxygen diffusion (Fig. 4A). The corresponding temporal decoupling is then evident in the time delay between the oxygen saturation peaks at the proximal and distal ends of the vein (Fig. 4B).

The conventional balloon model was also able to fit the measured HRFs, but its performance was inferior, particular for the late-time dynamics of the HRF. The balloon model also relied on venous CBV changes to obtain detailed fits, but these changes have not been observed experimentally. Moreover, balloon models generally fix the CBF/CMRO₂ response ratio n , and utilize an unexplained temporal delay

between these response components. By contrast, the arterial impulse model allows the CBF and CMRO₂ responses to vary appropriately based on oxygen mass balance within the dynamic constraints of our convection–diffusion transport model. Thus, the new model provides a more detailed, physiologically complete description of the BOLD HRF.

A number of previous models have included convection–diffusion transport. Huppert et al. (2007) combined convection–diffusion transport with a delayed-compliance Windkessel model to obtain excellent fits to experimental optical imaging data. However, this model was extremely complex, including many parameters that necessitated a much more intricate fitting procedure; moreover, this model still relied on a venous dilation effects. Also, a 3D convection–diffusion model was developed for direct application to the complex measured topology of the vascular network (Fang et al., 2008). This model was then applied and expanded with multiple imaging techniques (two-photon microscopy, confocal microscopy, and fMRI) to consider the effect of individual vascular compartments on the BOLD signal (Gagnon et al., 2015). The model predicted the precise dynamics of SO₂ profiles of the actual vascular network, providing detailed understanding of microvascular responses that compose the BOLD signal. While the detail and scope of this model is admirable, our approach has two substantial advantages. First, our model is much simpler. We used a cylindrical vascular unit with weighted volume fractions for capillary and venous compartments. Thus, we aimed to capture the dominant features of the oxygen transport in the simplest possible geometry. Accordingly, our model requires only two partial differential equations with six independent parameters for CBF and CMRO₂ responses. This simple model successfully fit the variable dynamics of BOLD HRF measurements across subjects and sessions, providing

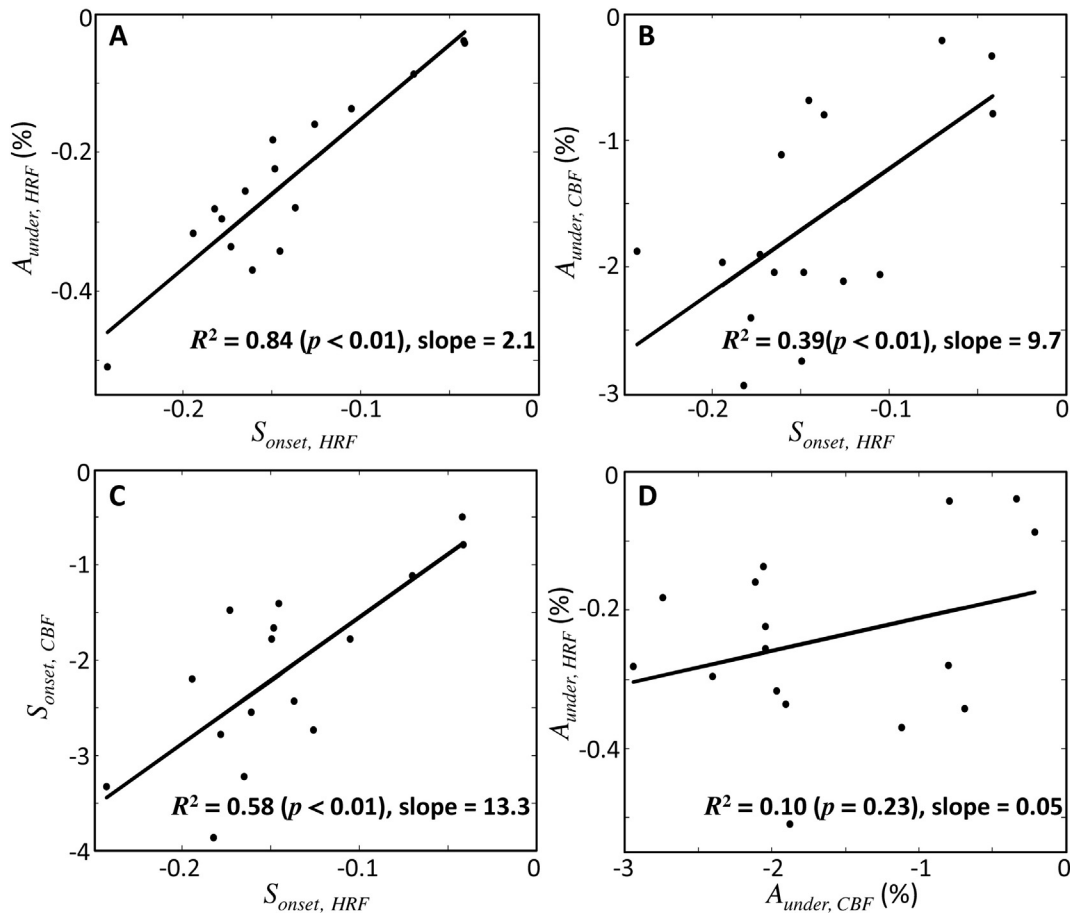


Fig. 8. Correlations among the undershoot parameters. (A) Strong linear correlation between measured HRF undershoot amplitude and HRF slope at undershoot onset. (B) Correlation between predicted CBF amplitude and HRF slope at undershoot onset. (C) Correlation of predicted CBF slope at undershoot onset with HRF slope at undershoot onset. (D) No significant correlation between HRF undershoot amplitude and CBF undershoot amplitude is observed.

physiologically reasonable estimates of corresponding CBF and CMRO₂ responses. Second, we do not assume a fixed ratio of CBF-to-CMRO₂ response; this ratio varies as needed to fit the measurements.

Various relationships between model parameters and the HRF measurements buttress our interpretation of neurovascular and neuro-metabolic coupling consequent to brief neural stimulation. The model fits to the measured HRFs show an offset linear relationship (approximately unity slope) between CBF and CMRO₂ peak amplitudes (Fig. 7A). Thus, averaged over each gray-matter ROI, CBF and CMRO₂ responses are predicted to vary together linearly, although CBF always exceeds CMRO₂.

This offset in the linearity between CBF and CMRO₂ is consistent with non-linearities in the BOLD response that have been observed and characterized in a number of reports (Friston et al., 2000; Pfeuffer et al., 2003; Vazquez and Noll, 1998). Largest non-linearities were generally observed for very short stimulation durations, in response to which we expect very low metabolic demand and very small CMRO₂ response. In these circumstances, our model predicts a breakdown in linearity because small increases CMRO₂ will create relatively large changes in CBF (see Eq. (14)).

The quasi-steady state approximation at the HRF peak explicitly describes this offset linear relationship (Fig. 7C). Consider the offset in this relationship, the second and third terms on the right side of Eq. (14). The offset corresponds to the disparity between oxygen supply and demand, because blood flow transports oxygen longitudinally far more effectively than the combination of dissociation and diffusion across the

blood vessel walls (Buxton and Frank, 1997; Uludag et al., 2004). At rest, the excess longitudinal transport maintains the requisite transmural gradient so that diffusion can supply the steady metabolic demand. During activation, this equilibrium is disturbed, resulting in the linear deviation from the resting state. The increase in metabolic demand requires a disproportionate increase in longitudinal oxygen supply. At the peak of the HRF, the quasi-steady-state relationship approximates this disparity by the slope term L/S , explicitly describing how the transient decoupling of supply and demand is simply a manifestation of the relative effectiveness of convection over dissociation and diffusion.

Moreover, there is an interesting non-linear relationship between the ratio of CBF-to-CMRO₂ amplitudes (n) and CMRO₂ amplitude (Fig. 7B). For over a decade, this ratio has been investigated to quantify the degree of the neurovascular decoupling, and a wide range of values have been reported; $n = 1.3$ –5 using fMRI (Davis et al., 1998; Griffeth and Buxton, 2011; Kastrup et al., 2002; Uludag et al., 2004), and $n = 6$ –10 for earlier studies using PET (Fox and Raichle, 1986; Fox et al., 1988). The arterial impulse model predicts that n is within the fMRI range. More importantly, the model shows that n is not a fixed value, but decreases with increasing CMRO₂ peak amplitude in a simple reciprocal relationship. A small metabolic demand increase requires a large relative boost in flow, but for large metabolic demand, n becomes approximately constant at its resting value. The volume-averaged CBF and CMRO₂ responses are more closely coupled to one other as metabolic demand increases. This closer coupling for strong-activation

regimes is consistent with the several studies that show a near-linear relationship between the BOLD response and simultaneous measurements of electrophysiology (Goense and Logothetis, 2008; Logothetis, 2003; Logothetis et al., 2001).

At the HRF peak, the quasi-steady-state solution also provides a reciprocal relationship, and the calculated n is nearly identical to that predicted from the full model (Fig. 7D). The quasi-steady-state solution explicitly quantifies how the reciprocal relationship (Eq. (15)) is a consequence of the offset-linear relationship (Eq. (14)). The quasi-steady state at the HRF peak is an approximation because the oxygen concentrations in the radial compartments (erythrocyte, plasma and extravascular) do not reach their peak values at the same time as the HRF. So, the temporal gradient for each compartment will not be precisely zero at the HRF peak. However, we find that the predicted blood flow amplitudes from the quasi-steady state analytic solutions (Figs. 7C–D, blue) are very similar to those from our full model (red).

The arterial impulse model thus quantifies the competition between convection and diffusion precisely, and this results in the variable n . The simple offset linear relationship between CBF and CMRO₂ emerges naturally from the mass balance (Eqs. (B.6)–(B.7)). In fact, this relationship is confirmed explicitly by the quasi-steady-state approximation to the dynamics despite the intricacies of the coupled systems of partial differential equations. Thus, the new model provides an extremely compact and logical description of BOLD response physiology.

The measured HRF undershoot amplitudes are very strongly correlated with their corresponding HRF undershoot-onset-slopes ($S_{\text{onset,HRF}}$), Fig. 8A. Strong undershoot is observed following fast decreases in the BOLD signal after the hyperoxic peak, while minimal undershoot is observed following slow decreases in the signal. This suggests a causal relationship between the dynamics driving the oxygen-concentration decrease and its subsequent minimum that is very similar to the underdamped behavior of the CBF. In fact, we also see strong linear correlations between the measured HRF undershoot-onset slope and both the CBF undershoot amplitude ($A_{\text{under,CBF}}$, Fig. 8B) and the corresponding CBF undershoot-onset slope ($S_{\text{onset,CBF}}$, Fig. 8C). These observations bolster the notion that the CBF response strongly affects the late-time dynamics of the HRF. Strong HRF undershoots are tightly coupled to the underdamped upstream arterial flow response.

However, the undershoot is not driven entirely by flow. In fact, the HRF undershoot amplitude is not strongly correlated with the corresponding CBF undershoot (Fig. 8D). Our model explains this as a variable contribution of late-time CMRO₂ to the HRF undershoot. The model predicts relatively fast increases and slow decays to baseline, consistent with previous CMRO₂ measurements (Masamoto and Tanishita, 2009; Vazquez et al., 2010). For example, we observe that some of the HRFs exhibit a slow return to baseline after undershoot, and the model explains this behavior as slow CMRO₂ decay to baseline (Fig. 5D). More experiments, perhaps using arterial spin labeling MRI to obtain simultaneous BOLD and flow measurements (Huppert et al., 2006; Liu and Brown, 2007; Liu and Wong, 2005; Liu et al., 2002), are needed to confirm our prediction of underdamped flow behavior.

The inclusion of inertia may also help to explain previously observed time-scale changes in the HRF produced by baseline CBF changes. For example, hyperemia induced by hypercapnia results in a slower CBF response to transient vasodilation and a slower HRF (Ances et al., 2001; Bakalova et al., 2001; Liu et al., 2004; Matsuura et al., 2000). Our model can explain this effect as an increase in baseline blood flow that increases the kinetic energy stored in blood flow, which thereby increases the inertial “stiffness” of the system, decreasing the CBF response frequency and slowing the CBF and HRF. However, these effects depend upon both the initial conditions and detailed topology of the vascular network, so further elaborations upon our model will be necessary to confirm such explanations.

The arterial impulse model requires solution of a system of partial differential equations. It is useful to have a simple analytic form for the BOLD HRF to enable analysis. The difference of two gamma-variate

functions is a popular heuristic form for the HRF. Motivated by the CBF and CMRO₂ responses in our model, we suggest an alternative form consisting of the difference between a damped sinusoid and a gamma-variate function, e.g.,: $F(t) = A_s \exp(-t/\tau_s) \sin(f_s t) - A_g t^{\frac{\epsilon}{g}} \exp(-t/\tau_g)$. This expression is closer to the predicted dynamics of the BOLD response, and will better match measured HRFs that exhibit oscillatory late-time behavior.

We emphasize that the arterial impulse model is only appropriate for the BOLD response evoked by brief neural activation. For longer periods of activation, there is substantial evidence that sluggish venous volume effects become significant, and it is likely that these effects can be modeled using the well-investigated balloon models. A full model of the BOLD response must include prompt arterial dilation and the slow venous dilation effects that have been well documented experimentally (Drew et al., 2011; Fernandez-Klett et al., 2010; Hillman et al., 2007; Huo et al., 2014).

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Appendix A

We derive the equations for the arterial impulse model of the BOLD signal. Total signal consists of two compartments: intravascular (subscript I) and extravascular tissue (subscript E):

$$S_{\text{total}} = v_I S_I + v_E S_E, \quad (\text{A.1})$$

where v is blood volume fraction. We ignore the signal change by arterial dilation, so the volume fraction of the each compartment is:

$$v_I = v_{Ic} + v_{Iv}, \quad \text{and} \quad (\text{A.2})$$

$$v_E = 1 - v_I, \quad (\text{A.3})$$

where subscript c and v represent capillary and vein respectively. We assume no volume change in both capillary and vein (Drew et al., 2011; Fernandez-Klett et al., 2010; Hillman et al., 2007; Vazquez et al., 2010). Therefore, the volume is constant for both resting (subscript 0), and activation (subscript 1). Resting signal is:

$$S_0 = v_I S_I + (1 - v_I) S_E. \quad (\text{A.4})$$

During activation, the signal is:

$$S_1 = v_I S_I \exp(-TE \cdot \Delta R_{2I}^*) + (1 - v_I) S_E \exp(-TE \cdot \Delta R_{2E}^*), \quad (\text{A.5})$$

where TE is echo time, ΔR_2^* is the change in the MR signal relaxation rate during activation. The BOLD signal is fractional change in the MR signal:

$$\delta S = \frac{\Delta S}{S_0} = \frac{S_1 - S_0}{S_0} = \frac{S_1}{S_0} - 1 = \frac{v_I S_I \exp(-TE \cdot \Delta R_{2I}^*) + (1 - v_I) S_E \exp(-TE \cdot \Delta R_{2E}^*)}{v_I S_I + (1 - v_I) S_E} - 1. \quad (\text{A.6})$$

Substituting ϵ , the ratio of intrinsic intravascular signal to extravascular signal, into Eq. (A.6):

$$\delta S = \frac{1}{\epsilon v_I + (1 - v_I)} [\epsilon v_I \cdot \exp(-TE \cdot \Delta R_{2I}^*) + (1 - v_I) \exp(-TE \cdot \Delta R_{2E}^*)] - 1. \quad (\text{A.7})$$

Eq. (A.7) can be rearranged as Eq. (1) in the manuscript.

Appendix B

B.1. Full solutions

We derive partial differential equations for mass balance between three compartments (erythrocyte, plasma, and extravascular tissue) in the capillary:

$$\frac{\partial Q_h}{\partial t} = -\frac{F(z, t)}{c_h} - U(t) \frac{\partial Q_h}{\partial z}, \quad (\text{B.1})$$

$$\frac{\partial Q_p}{\partial t} = \frac{F(z, t)}{c_p} - A(Q_p - Q_e) - U(t) \frac{\partial Q_p}{\partial z}, \quad (\text{B.2})$$

$$\frac{\partial Q_e}{\partial t} = A \frac{c_p}{c_e} (Q_p - Q_e) - \frac{c_h + c_p}{v_c c_e} \Gamma(t), \quad (\text{B.3})$$

where Q is concentration, F is the oxygen dissociation flux, U is flow speed, A is a diffusion rate constant, c is volume per length, and subscript h , p , and e represent erythrocyte, plasma, and extravascular tissue respectively. A weighted sum of Eqs. (B.1) and (B.2) eliminates the oxygen-dissociation flux term, $F(z, t)$:

$$\frac{\partial Q_p}{\partial t} + \frac{c_h}{c_p} \frac{\partial Q_h}{\partial t} = -A(Q_p - Q_e) - U(t) \left(\frac{\partial Q_p}{\partial z} + \frac{c_h}{c_p} \frac{\partial Q_h}{\partial z} \right). \quad (\text{B.4})$$

To deal with the non-linear character of oxygen dissociation, we can approximate the Hill equation using a quadratic fit to describe oxygen dissociation within a limited range of oxygen saturation, 50–93% O_2 saturation, so:

$$Q_h(z, t) = k_1 Q_p^2(z, t) + k_2 Q_p(z, t) + k_3, \quad (\text{B.5})$$

where $k_1 = -1043$, $k_2 = 197.74$ and $k_3 = -0.82$. We substitute this approximation into Eq. (B.4) to describe oxygen mass balance for the plasma compartment including oxygen dissociation:

$$\frac{\partial Q_p}{\partial t} = -U(t) \frac{\partial Q_p}{\partial z} - \frac{A(Q_p - Q_e)}{1 + \frac{Ht}{1-Ht} (2k_1 Q_p + k_2)}. \quad (\text{B.6})$$

We also can rewrite Eq. (B.3) for the extravascular compartment using volume ratio $\alpha = (C_h + C_p)/C_e$, and hematocrit, Ht :

$$\frac{\partial Q_e}{\partial t} = \alpha \left[A(1-Ht)(Q_p - Q_e) - \frac{\Gamma(t)}{v_c} \right]. \quad (\text{B.7})$$

Eqs. (B.6) and (B.7) are our chosen form for numerical solution of the transient oxygen mass-balance equations.

For the vein, there are only the flow and dissociation terms in the mass balance, because we assume no oxygen transport to the tissue:

$$\frac{\partial Q_h}{\partial t} = -\frac{F(z, t)}{c_h} - U(t) \frac{\partial Q_h}{\partial z}, \quad (\text{B.8})$$

$$\frac{\partial Q_p}{\partial t} = \frac{F(z, t)}{c_p} - U(t) \frac{\partial Q_p}{\partial z}. \quad (\text{B.9})$$

Use Eq. (B.6) to include oxygen dissociation, and form the weighted sum of Eqs. (B.8) and (B.9) to eliminate F :

$$\left[1 - \frac{c_h}{c_p} (2k_1 + k_2) \right] \frac{\partial Q_p}{\partial t} = U(t) \left[\frac{c_h}{c_p} (2k_1 + k_2) - 1 \right] \frac{\partial Q_p}{\partial z}. \quad (\text{B.10})$$

Thus, venous mass balance equation is simply:

$$\frac{\partial Q_p}{\partial t} = -U(t) \frac{\partial Q_p}{\partial z}. \quad (\text{B.11})$$

This, together with Eq. (B.6), defines oxygen transport in the vein.

B.2. Steady-state solutions

At rest, we can approximate the dynamics by setting all time derivatives to zero. In the vein, this simply forces all oxygen concentrations to be spatially constant. In the capillary, the dynamics are more complex. Combining Eqs. (B.6) and (B.7) in the steady state yields:

$$U_0 \frac{dQ_p}{dz} = -\frac{\Gamma_0}{v_c(1-Ht) \left[1 + \frac{Ht}{1-Ht} (2k_1 Q_p + k_2) \right]}. \quad (\text{B.12})$$

Applying the boundary condition, $Q_p = Q_{p,s}$, at the proximal end ($z = 0$):

$$\left(Q_p + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2 = -\frac{\Gamma_0}{v_c(1-Ht)U_0} z + \left(Q_{p,s} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2. \quad (\text{B.13})$$

Therefore, the analytic steady-state solution of the system is:

$$Q_p = -\frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} + \sqrt{-\frac{\Gamma_0}{v_c(1-Ht)U_0} z + \left(Q_{p,s} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2}. \quad (\text{B.14})$$

We can obtain the capillary length (L) by applying the distal boundary condition, $Q_p = Q_{p,L}$, at $z = L$:

$$L = -\frac{v_c(1-Ht)U_0}{\Gamma_0} \left[\left(Q_{p,s} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2 - \left(Q_{p,L} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2 \right]. \quad (\text{B.15})$$

At the peak of the HRF, we can assume an approximate steady state because the temporal gradient is nearly zero, a similar relationship to Eq. (B.15) can be held between flow speed, $U_{act} = U_0 + \Delta U$, and $CMRO_2$, $\Gamma_{act} = \Gamma_0 + \Delta \Gamma$ at HRF peak:

$$L = -\frac{v_c(1-Ht)(U_0 + \Delta U)}{(\Gamma_0 + \Delta \Gamma)} \left[\left(Q_{p,s} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2 - \left(Q_{p,L} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2 \right]. \quad (\text{B.16})$$

Let

$$S = v_c(1-Ht) \left[\left(Q_{p,s} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2 - \left(Q_{p,L} + \frac{1 + \frac{Ht}{1-Ht} k_2}{2 \frac{Ht}{1-Ht} k_1} \right)^2 \right], \quad (\text{B.17})$$

in Eq. (B.16), and one obtains manuscript Eq. (14).

Appendix C

We reconstruct a balloon model for comparison purpose. We use the modified balloon model (Buxton et al., 2004). The basic BOLD equation is:

$$\frac{\Delta S(t)}{S} = v_v[a_1(1-q(t)) - a_2(1-x(t))], \quad (\text{C.1})$$

where v_v is venous volume fraction, q is normalized total deoxyhemoglobin, x is the normalized volume of the venous balloon, and a_1 and a_2 are dimensionless parameters. The mass balance of the balloon model for blood and deoxyhemoglobin is:

$$\frac{dq}{dt} = \frac{1}{\tau_{MTT}} \left[m(t) - \frac{q(t)}{x(t)} f_{out}(x, t) \right], \quad (C.2)$$

$$\frac{dx}{dt} = \frac{1}{\tau_{MTT}} [f(t) - f_{out}(x, t)], \quad (C.3)$$

$$f_{out}(x, t) = x^{\frac{1}{\alpha}} + \tau \frac{dx}{dt}, \quad (C.4)$$

where m is normalized CMRO₂, f is normalized CBF, f_{out} is normalized outflow from the balloon, τ_{MTT} is mean transit time through the balloon at rest, α is flow-volume coefficient at rest, and τ is a time constant. The forms of the CBF and CMRO₂ responses are postulated as a gamma-variate function $h(t)$. We assume that these two transient impulse responses in CBF and CMRO₂ are driven by neural activity, which we model as a 2-second duration rectangular pulse $N(t)$. Then, the CBF and CMRO₂ responses for activation are obtained by convolution with $N(t)$:

$$f(t) = 1 + (f_1 - 1) h_f(t - \delta t_f) * N(t), \quad (C.5)$$

$$m(t) = 1 + (m_1 - 1) h_m(t - \delta t_m) * N(t), \quad (C.6)$$

where f_1 and m_1 are scaling amplitude parameters, δt_f and δt_m are delay time of CBF and CMRO₂ responses. The ratio of CBF to CMRO₂ responses, $n = (f_1 - 1) / (m_1 - 1)$ is fixed ($n = 2$). Time delay of CBF relative to CMRO₂ responses ($\delta t = \delta t_f - \delta t_m$) is assumed for initial delay of the HRF.

To fit the balloon model to our measured HRFs, we performed nonlinear optimization with six parameters: damping time and shape coefficient of the gamma-variate function for each response, scaling amplitude parameter (f_1) and relative time delay (δt).

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